

# Parameter Sensitivity Analysis for Hypersonic Viscous Flow using a Discrete Adjoint Approach

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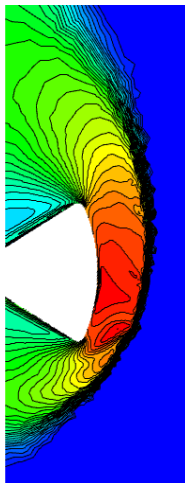
Mechanical Engineering  
University of Wyoming

January 4, 2010

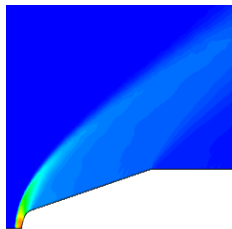
## Outline

- Introduction
- Overview of Flow Solver and Physical Models
- Solution Scheme Details
- Sensitivity Formulation
- Flow and Sensitivity Results for Perfect Gas Model
- Flow and Sensitivity Results for Real Gas Model
- Conclusion

- Simulation of complex problems rely heavily on empirical relations
- Relations can require hundreds of parameters to define
- Sensitivity and uncertainty can enhance analysis and design capability
- Sampling currently used due to nonlinear nature of flows
  - Thousands of flow solutions required
  - Computationally expensive



- Localized sensitivity calculated using flow adjoint
- Sensitivity to large number of inputs with cost approximately equal to flow solve
- Possibilities for uncertainty quantification, adaptation and simulation optimization.
- Should be possible to augment weaknesses of sampling with an adjoint based approach



- Navier Stokes Equations:

$$\frac{\partial \mathbf{U}}{\partial t} + \nabla \cdot \vec{F}(\mathbf{U}) = \nabla \cdot \vec{F}_v(\mathbf{U}) + \mathbf{S}(\mathbf{U}) \quad (1)$$

- Two dimensional, cell-centered finite volume solver using unstructured triangles and/or quadrilaterals
- Solver uses a fully implicit, pseudo-time stepping method
- Perfect gas and Real gas models examined

- Perfect gas variables

$$\mathbf{U} = \begin{Bmatrix} \rho \\ \rho \vec{u} \\ \rho e_t \end{Bmatrix} \quad \vec{F} = \begin{Bmatrix} \rho \vec{u} \\ \rho \vec{u} \otimes \vec{u} + P \\ \rho \vec{u} h_t \end{Bmatrix} \quad \vec{F}_v = \begin{Bmatrix} 0 \\ \underline{\tau} \\ \underline{\tau} \cdot \vec{u} - \vec{q} \end{Bmatrix}$$

- Sutherland's Law used for viscosity
- 5 Parameters required to define model:
  - Ratio of Specific Heats  $\gamma$
  - Reynolds Number
  - Prandtl Number
  - Two constants within Sutherland's Law

- 5 species, Two Temperature Real Gas Model

$$\mathbf{U} = \begin{Bmatrix} \rho_s \\ \rho \vec{u} \\ \rho e_t \\ \rho e_v \end{Bmatrix} \quad \vec{F} = \begin{Bmatrix} \rho_s \vec{u} \\ \rho \vec{u} \otimes \vec{u} + P \\ \rho \vec{u} h_t \\ \rho \vec{u} h_v \end{Bmatrix} \quad \mathbf{S} = \begin{Bmatrix} \omega_s \\ 0 \\ 0 \\ \sum_s \omega_s \hat{D}_{v,s} + Q_{T-v} \end{Bmatrix}$$

$$\vec{F}_v = \begin{Bmatrix} -\rho_s \tilde{V}_s \\ \underline{\tau} \\ \underline{\tau} \cdot \vec{u} - \vec{q} - \vec{q}_v - \sum_s h_{t,s} \rho_s \tilde{V}_s \\ -\sum_s h_{v,s} \rho_s \tilde{V}_s - \vec{q}_v \end{Bmatrix}$$

- Dunn-Kang chemical kinetics model used
- Transport quantities calculated using curve fits from Blottner *et al*
- Approximately 250 constants required to define physical model

- Solution marched to steady state using implicit pseudo-time stepping
- Method of Lines:

$$\frac{d\mathbf{U}}{dt} + \mathbf{R}(\mathbf{U}) = 0 \quad (2)$$

- BDF1 discretization used for pseudo-time derivative
- Unsteady residual given by:

$$\mathbf{J}(\mathbf{U}^n, \mathbf{U}^{n-1}) = \frac{\mathbf{U}^n - \mathbf{U}^{n-1}}{\Delta t} + \mathbf{R}(\mathbf{U}^n) \quad (3)$$

- Nonlinear equation  $\mathbf{J}(\mathbf{U}^n, \mathbf{U}^{n-1}) = 0$  solved approximately at each time step



- Fixed number of inexact Newton iterations performed per time step ( $\sim 10$ )

$$\delta \mathbf{U}^k = - [P]^{-1} \mathbf{J}(\mathbf{U}^k, \mathbf{U}^{n-1}) \quad (4)$$

$$\mathbf{U}^{k+1} = \mathbf{U}^k + \lambda \delta \mathbf{U}^k \quad (5)$$

- $[P]$  chosen to approximate  $\frac{\partial \mathbf{J}}{\partial \mathbf{U}^k}$ , 1st order Van-Leer-Hänel
- Preconditioner matrix and transport quantities calculated once per time step and frozen.
- Global time stepping used for start-up, local time stepping for full convergence
- $\lambda$  used to keep updates sensible

# Spatial Discretization

- Gradient reconstruction of primitives
- Green-Gauss contour integration used to calculate gradients
- Smooth Van Albada Limiter with Pressure Switch used:

$$\Psi_k = \max(0, 1 - K\nu_k) \frac{1}{\Delta^-} \frac{(\Delta^{+2} + \varepsilon^2)\Delta^- + 2\Delta^{-2}\Delta^+}{\Delta^{+2} + 2\Delta^- + \Delta^-\Delta^+ + \varepsilon^2} \quad (6)$$

$$\nu_i = \frac{\sum_k |P_R - P_L|}{\sum_k P_R + P_L} \quad (7)$$

- Face based Gradients calculated using averaging and correction term:

$$\nabla \mathbf{V}_k = \tilde{\nabla} \mathbf{V} + \frac{\mathbf{V}_R - \mathbf{V}_L - \tilde{\nabla} \mathbf{V} \cdot \Delta \vec{T}}{|\Delta \vec{T}|} \frac{\Delta \vec{T}}{|\Delta \vec{T}|} \quad (8)$$

- Inviscid Flux Calculated Using AUSM+UP flux function with Frozen Speed of Sound

# Sensitivity Derivation

- Let the objective and constraint have following functional dependence

$$L = L(D, \mathbf{U}(D)) \quad (9)$$

$$\mathbf{R} = \mathbf{R}(D, \mathbf{U}(D)) = 0 \quad (10)$$

- Objective and Constraint may be differentiated using the Chain rule

$$\frac{dL}{dD} = \frac{\partial L}{\partial D} + \frac{\partial L}{\partial \mathbf{U}} \frac{\partial \mathbf{U}}{\partial D} \quad (11)$$

$$\frac{d\mathbf{R}}{dD} = \frac{\partial \mathbf{R}}{\partial D} + \frac{\partial \mathbf{R}}{\partial \mathbf{U}} \frac{\partial \mathbf{U}}{\partial D} = 0 \quad (12)$$

- Solve Constraint Equation for  $\frac{\partial \mathbf{U}}{\partial D}$

# Sensitivity Derivation

- Forward Sensitivity Equation Given by:

$$\frac{dL}{dD} = \frac{\partial L}{\partial D} - \frac{\partial L}{\partial \mathbf{U}} \frac{\partial \mathbf{R}^{-1}}{\partial \mathbf{U}} \frac{\partial \mathbf{R}}{\partial D} \quad (13)$$

- Transpose Equation

$$\frac{dL^T}{dD} = \frac{\partial L^T}{\partial D} - \frac{\partial \mathbf{R}^T}{\partial D} \frac{\partial \mathbf{R}^{-T}}{\partial \mathbf{U}} \frac{\partial L^T}{\partial \mathbf{U}} \quad (14)$$

- Define Flow Adjoint with Equation:

$$\frac{\partial \mathbf{R}^T}{\partial \mathbf{U}} \boldsymbol{\Lambda} = -\frac{\partial L^T}{\partial \mathbf{U}} \quad (15)$$

- Sensitivity Calculated by:

$$\frac{dL^T}{dD} = \frac{\partial L^T}{\partial D} + \frac{\partial \mathbf{R}^T}{\partial D} \boldsymbol{\Lambda} \quad (16)$$

# Parameter Sensitivity

- For Model Parameters,  $D$  dependence enters through field variables  $\mu$

$$L = L(\mathbf{U}(D), \mu(D, \mathbf{U}(D))) \quad (17)$$

$$\mathbf{R} = \mathbf{R}(\mathbf{U}(D), \mu(D, \mathbf{U}(D))) \quad (18)$$

- Sutherland's Law Example

$$\frac{\mu}{\mu_{ref}} = \frac{C_1 T^{3/2}}{T + S} \quad (19)$$

- Forward Sensitivity Equation for Model Parameters

$$\frac{dL}{dD} = \frac{\partial L}{\partial \mu} \frac{\partial \mu}{\partial D} + \left( \frac{\partial L}{\partial \mathbf{U}} + \frac{\partial L}{\partial \mu} \frac{\partial \mu}{\partial \mathbf{U}} \right) \frac{\partial \mathbf{U}}{\partial D} \quad (20)$$

# Parameter Sensitivity

- Adjoint Sensitivity Equation for Model Parameters

$$\frac{\partial L^T}{\partial D} = \frac{\partial \mu^T}{\partial D} \left( \frac{\partial L^T}{\partial \mu} + \frac{\partial \mathbf{R}^T}{\partial \mu} \boldsymbol{\Lambda} \right) \quad (21)$$

- Flow Adjoint Found by Solving Equation:

$$\left[ \frac{\partial \mathbf{R}}{\partial \mathbf{U}} + \frac{\partial \mathbf{R}}{\partial \mu} \frac{\partial \mu}{\partial \mathbf{U}} \right]^T \boldsymbol{\Lambda} = - \left( \frac{\partial L^T}{\partial \mathbf{U}} + \frac{\partial \mu^T}{\partial \mathbf{U}} \frac{\partial L^T}{\partial \mu} \right) \quad (22)$$

- Adjoint Equation solved with Defect Correction:

$$[P]^T \delta \boldsymbol{\Lambda}^k = - \frac{\partial L^T}{\partial \mathbf{U}} - \left[ \frac{\partial \mu^T}{\partial \mathbf{U}} \frac{\partial \mathbf{R}^T}{\partial \mu} + \frac{\partial \mathbf{R}^T}{\partial \mathbf{U}} \right] \boldsymbol{\Lambda}^k \quad (23)$$

$$\boldsymbol{\Lambda}^{k+1} = \boldsymbol{\Lambda}^k + \delta \boldsymbol{\Lambda}^k \quad (24)$$

# Field Variable Sensitivity

- Set  $\frac{\partial \mu}{\partial D} = 1$  and  $\frac{\partial \mu}{\partial \mathbf{U}} = 0$ :

$$\frac{\partial L^T}{\partial \mu} = \frac{\partial L^T}{\partial \mu} + \frac{\partial R^T}{\partial \mu} \Lambda_\mu \quad (25)$$

- Formally, Adjoint Solution with Frozen  $\mu$  required:

$$\left[ \frac{\partial \mathbf{R}}{\partial \mathbf{U}} \right]_\mu^T \Lambda_\mu = - \left( \frac{\partial L}{\partial \mathbf{U}} \right)_\mu^T \quad (26)$$

- Field Variables defined throughout domain (at cell centers or face centers)
- May be used for Uncertainty Propagation or Model Adaptation

$$\delta L^2 = \sum_i \frac{\partial L^2}{\partial \mu_i} \delta \mu_i^2(\mathbf{u}_i) \quad (27)$$

# Perfect Gas Results

- 5 km/s cylinder test case
- Fixed Wall temperature
- Results compared against LAURA and FUN2D

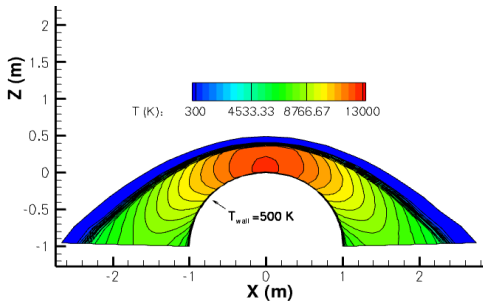
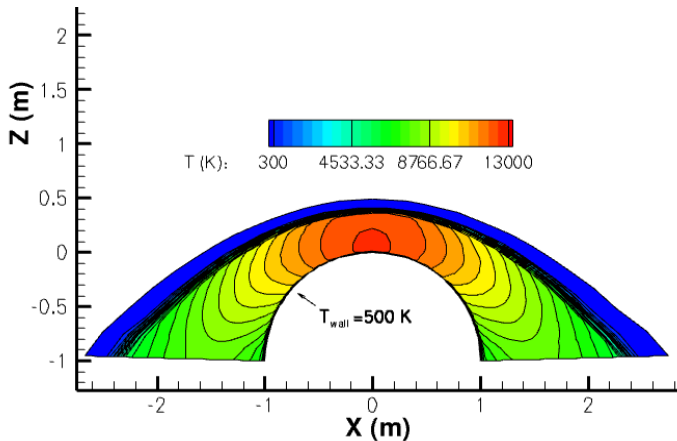


Table: Benchmark Flow Conditions

$V_\infty =$	5 km/s
$\rho_\infty =$	$0.001 \text{ kg/m}^3$
$T_\infty =$	200 K
$T_{wall} =$	500 K
$M_\infty =$	17.605
$Re_\infty =$	753,860
$Pr_\infty =$	0.72

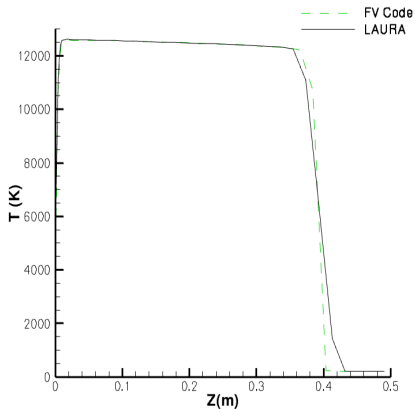


# Perfect Gas Results

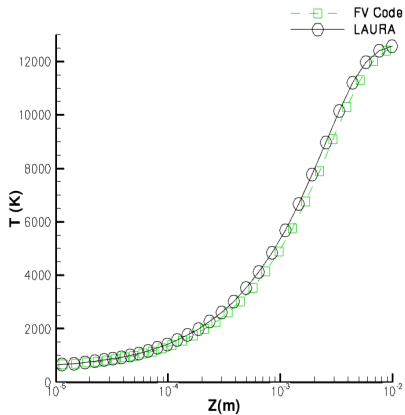


*Temperature Contour for 5 km/s case*

# Perfect Gas Results

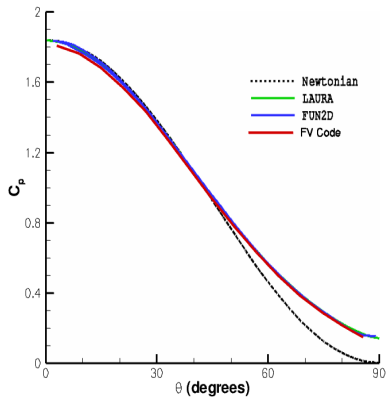


Temperature along Stagnation Streamline

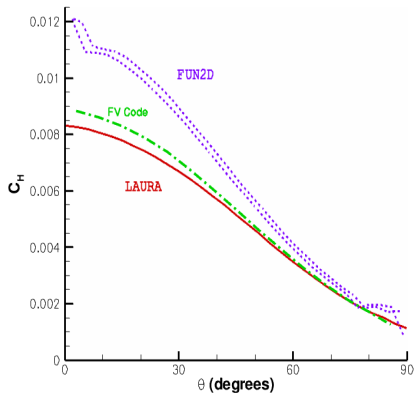


Temperature along Stagnation Streamline (Boundary Layer)

# Perfect Gas Results



Surface Pressure Distribution



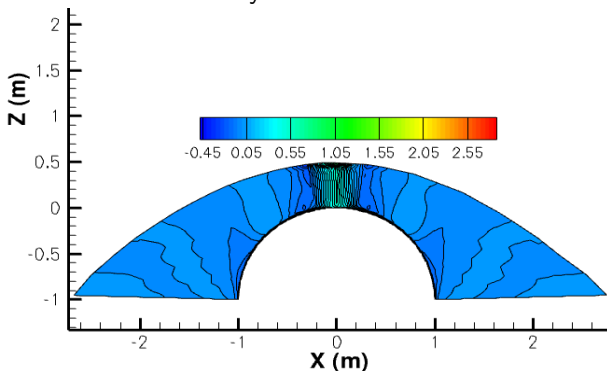
Surface Heating Distribution

# Perfect Gas Sensitivity

- Geometric and Parameter Sensitivities for 5 km/s Benchmark Case
- Sensitivities computed for Integrated Surface heating Objective:

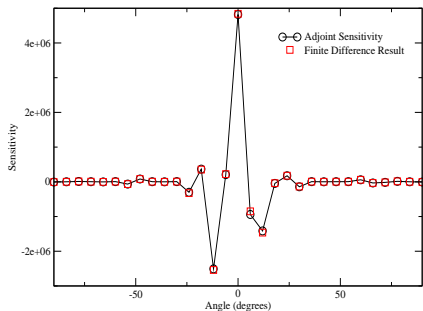
$$L = \int_A -k \nabla T \cdot \vec{n} dA \quad (28)$$

- Sensitivities Validated using Finite Difference
- Adjoint Solution for Velocity



# Geometric Sensitivity

- Sensitivity of Surface Heating to surface geometry calculated
- Normal displacement of surface grid points used as design variable
- 31 total design variables



*Heat Flux Sensitivity to Surface Point Displacements*

# Parameter Sensitivity

- Sensitivity to Perfect Gas Parameter  $\gamma$
- Fixed Freestream Velocity and Fixed Freestream Mach Number Considered

Table: Sensitivity of Surface Heating to  $\gamma$

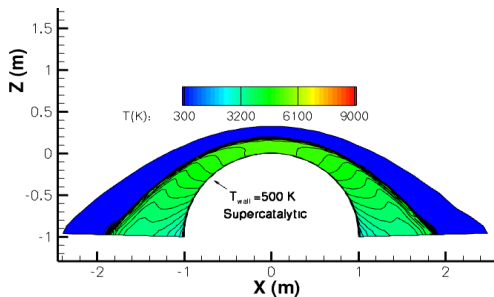
	Fixed Velocity	Fixed Mach Number
Objective Value	$1.628 \times 10^{-2}$	$1.628 \times 10^{-2}$
Finite Difference	$-3.111 \times 10^{-2}$	$-1.198 \times 10^{-2}$
Adjoint	$-3.109 \times 10^{-2}$	$-1.206 \times 10^{-2}$
Relative Error	$7.279 \times 10^{-4}$	$7.186 \times 10^{-4}$

# Real Gas Results

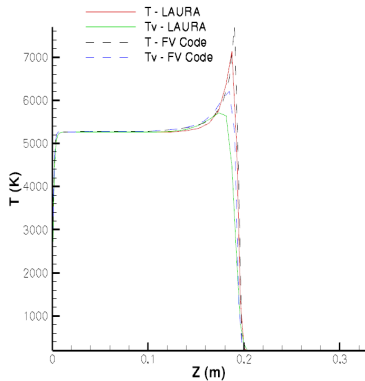
- 5 km/s cylinder test case
- Fixed Wall temperature
- Super-catalytic Wall
- Results compared with LAURA

Table: Benchmark Flow Conditions

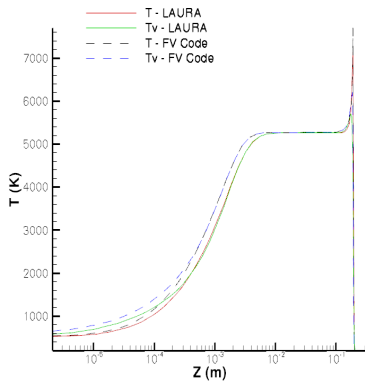
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$\rho_\infty =$	$0.001 \text{ kg/m}^3$
$T_\infty =$	200 K
$T_{wall} =$	500 K
$M_\infty =$	17.605
$Re_\infty =$	753,860
$Pr_\infty =$	0.72



# Real Gas Results



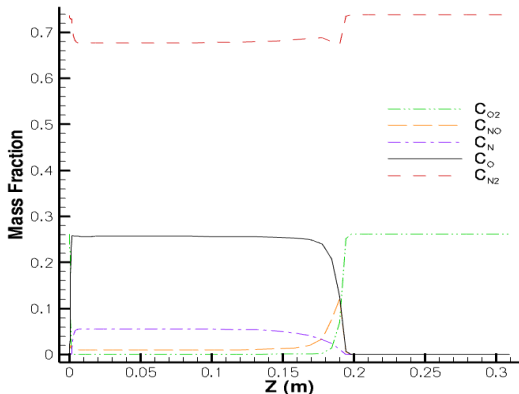
Temperature along Stagnation Streamline



Temperature along Stagnation Streamline (Log Scale)

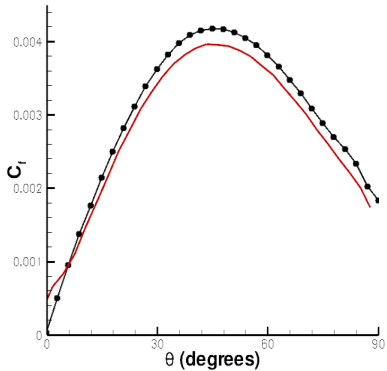


# Real Gas Results

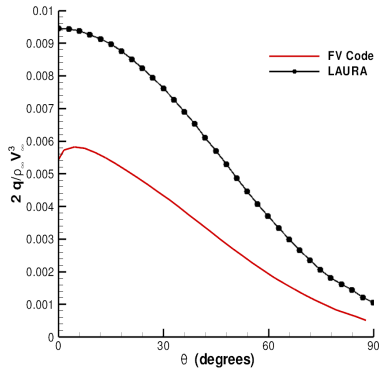


*Mass Fraction along Stagnation Streamline for 5 km/s case*

# Real Gas Results



*Skin Friction Distribution*



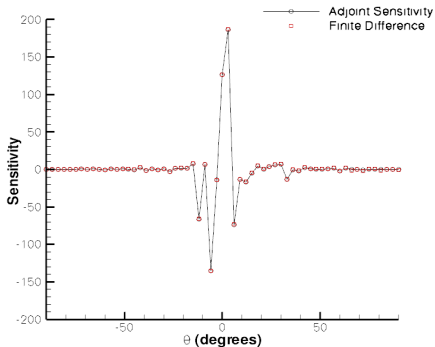
*Surface Heating Distribution*

# Real Gas Sensitivity

- Sensitivities computed for Integrated Surface heating Objective:

$$L = - \int_A k \nabla T \cdot \vec{n} + k_v \nabla T_v \cdot \vec{n} dA \quad (29)$$

- Sensitivities Validated using Finite Difference
- Geometric Sensitivity, 61 Design Variables



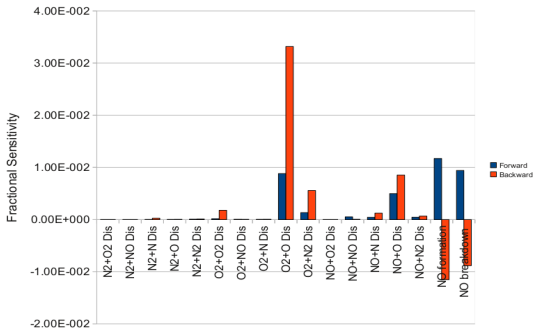
# Real Gas Sensitivity

- Sensitivity of Surface Heating to Arrhenius Coefficients:

$$K_f = C_f T_a^{\eta_f} e^{-\frac{E_{a,f}}{kT_a}} \quad (30)$$

$$K_b = C_b T_a^{\eta_b} e^{-\frac{E_{a,b}}{kT_a}} \quad (31)$$

- Sensitivities Expressed as fractional changes (i.e.  $\frac{dL/L}{dD/D}$ )

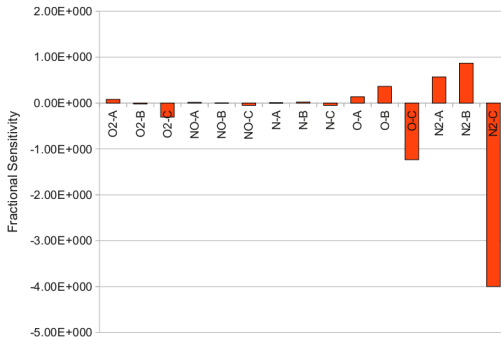


# Real Gas Sensitivity

- Sensitivity of Surface Heating to Species Viscosity Curve Fit Parameters:

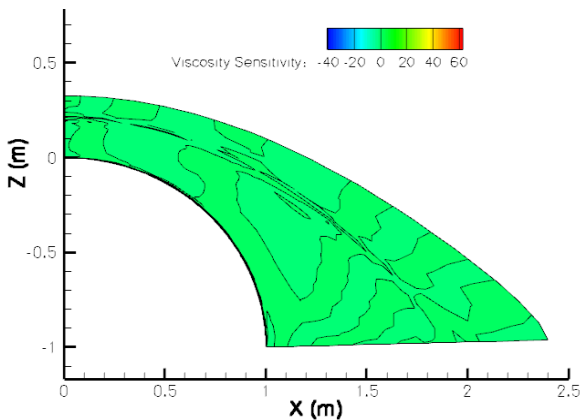
$$\mu_s = 0.1e^{(A_s \ln(T) + B_s) \ln(T) + C_s} \quad (32)$$

- Significantly Higher Sensitivity than Reaction Parameters

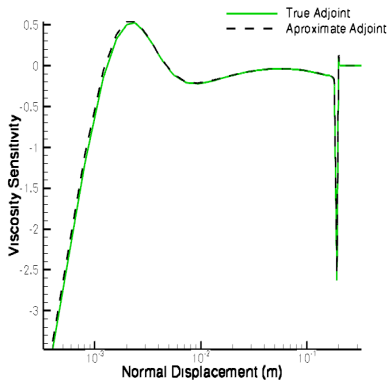


# Real Gas Sensitivity

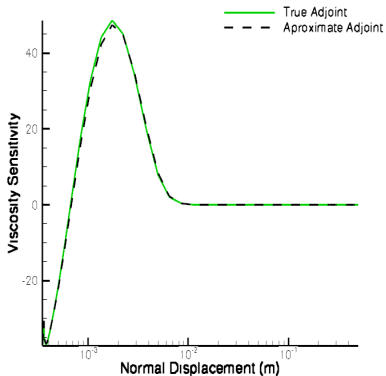
- Sensitivity of Surface Heating to Face-centered Viscosity throughout Domain
- 7800 Faces within Computational Grid
- Exact and Approximate Adjoints used to Compute Sensitivity



# Real Gas Sensitivity



*Viscosity Sensitivity along Stagnation Streamline*



*Viscosity Sensitivity at 45 degrees*

## Conclusions:

- Sensitivity to large number of parameters with minimal effort possible with adjoint
- Parameter sensitivity can be used to determine most important model components
- Field variable sensitivity possible; identifying regions/ranges of greatest importance

## Future Work:

- Extend valid range of sensitivities by including higher order terms
- Investigate simulation adaptation using adjoint
- Explore hybrid sensitivity/sampling approaches to uncertainty quantification